

NAG C Library Function Document

nag_zhetrf (f07mrc)

1 Purpose

nag_zhetrf (f07mrc) computes the Bunch–Kaufman factorization of a complex Hermitian indefinite matrix.

2 Specification

```
void nag_zhetrf (Nag_OrderType order, Nag_UploType uplo, Integer n, Complex a[],
                Integer pda, Integer ipiv[], NagError *fail)
```

3 Description

nag_zhetrf (f07mrc) factorizes a complex Hermitian matrix A , using the Bunch–Kaufman diagonal pivoting method. A is factorized as either $A = PUDU^H P^T$ if **uplo** = **Nag_Upper**, or $A = PLDL^H P^T$ if **uplo** = **Nag_Lower**, where P is a permutation matrix, U (or L) is a unit upper (or lower) triangular matrix and D is an Hermitian block diagonal matrix with 1 by 1 and 2 by 2 diagonal blocks; U (or L) has 2 by 2 unit diagonal blocks corresponding to the 2 by 2 blocks of D . Row and column interchanges are performed to ensure numerical stability while keeping the matrix Hermitian.

This method is suitable for Hermitian matrices which are not known to be positive-definite. If A is in fact positive-definite, no interchanges are performed and no 2 by 2 blocks occur in D .

4 References

Golub G H and Van Loan C F (1996) *Matrix Computations* (3rd Edition) Johns Hopkins University Press, Baltimore

5 Parameters

- 1: **order** – Nag_OrderType *Input*
On entry: the **order** parameter specifies the two-dimensional storage scheme being used, i.e., row-major ordering or column-major ordering. C language defined storage is specified by **order** = **Nag_RowMajor**. See Section 2.2.1.4 of the Essential Introduction for a more detailed explanation of the use of this parameter.
Constraint: **order** = **Nag_RowMajor** or **Nag_ColMajor**.
- 2: **uplo** – Nag_UploType *Input*
On entry: indicates whether the upper or lower triangular part of A is stored and how A has been factorized, as follows:
 if **uplo** = **Nag_Upper**, the upper triangular part of A is stored and A is factorized as $PUDU^H P^T$, where U is upper triangular;
 if **uplo** = **Nag_Lower**, the lower triangular part of A is stored and A is factorized as $PLDL^H P^T$, where L is lower triangular.
Constraint: **uplo** = **Nag_Upper** or **Nag_Lower**.
- 3: **n** – Integer *Input*
On entry: n , the order of the matrix A .
Constraint: $n \geq 0$.

4: **a**[*dim*] – Complex *Input/Output*

Note: the dimension, *dim*, of the array **a** must be at least $\max(1, \mathbf{pda} \times \mathbf{n})$.

If **order** = **Nag_ColMajor**, the (*i*, *j*)th element of the matrix *A* is stored in **a**[(*j* – 1) × **pda** + *i* – 1] and if **order** = **Nag_RowMajor**, the (*i*, *j*)th element of the matrix *A* is stored in **a**[(*i* – 1) × **pda** + *j* – 1].

On entry: the *n* by *n* Hermitian matrix *A*. If **uplo** = **Nag_Upper**, the upper triangle of *A* must be stored and the elements of the array below the diagonal are not referenced; if **uplo** = **Nag_Lower**, the lower triangle of *A* must be stored and the elements of the array above the diagonal are not referenced.

On exit: the upper or lower triangle of *A* is overwritten by details of the block diagonal matrix *D* and the multipliers used to obtain the factor *U* or *L* as specified by **uplo**.

5: **pda** – Integer *Input*

On entry: the stride separating row or column elements (depending on the value of **order**) of the matrix *A* in the array **a**.

Constraint: **pda** ≥ max(1, **n**).

6: **ipiv**[*dim*] – Integer *Output*

Note: the dimension, *dim*, of the array **ipiv** must be at least max(1, **n**).

On exit: details of the interchanges and the block structure of *D*.

More precisely, if **ipiv**[*i* – 1] = *k* > 0, *d*_{*ii*} is a 1 by 1 pivot block and the *i*th row and column of *A* were interchanged with the *k*th row and column.

If **uplo** = **Nag_Upper** and **ipiv**[*i* – 2] = **ipiv**[*i* – 1] = –*l* < 0, $\begin{pmatrix} d_{i-1,i-1} & d_{i,i-1} \\ d_{i,i-1} & d_{ii} \end{pmatrix}$ is a 2 by 2 pivot block and the (*i* – 1)th row and column of *A* were interchanged with the *l*th row and column.

If **uplo** = **Nag_Lower** and **ipiv**[*i* – 1] = **ipiv**[*i*] = –*m* < 0, $\begin{pmatrix} d_{ii} & d_{i+1,i} \\ d_{i+1,i} & d_{i+1,i+1} \end{pmatrix}$ is a 2 by 2 pivot block and the (*i* + 1)th row and column of *A* were interchanged with the *m*th row and column.

7: **fail** – NagError * *Output*

The NAG error parameter (see the Essential Introduction).

6 Error Indicators and Warnings

NE_INT

On entry, **n** = *<value>*.

Constraint: **n** ≥ 0.

On entry, **pda** = *<value>*.

Constraint: **pda** > 0.

NE_INT_2

On entry, **pda** = *<value>*, **n** = *<value>*.

Constraint: **pda** ≥ max(1, **n**).

NE_SINGULAR

The block diagonal matrix *D* is exactly singular.

NE_ALLOC_FAIL

Memory allocation failed.

NE_BAD_PARAM

On entry, parameter $\langle value \rangle$ had an illegal value.

NE_INTERNAL_ERROR

An internal error has occurred in this function. Check the function call and any array sizes. If the call is correct then please consult NAG for assistance.

7 Accuracy

If **uplo** = **Nag_Upper**, the computed factors U and D are the exact factors of a perturbed matrix $A + E$, where

$$|E| \leq c(n)\epsilon P|U||D||U^H|P^T,$$

$c(n)$ is a modest linear function of n , and ϵ is the *machine precision*.

If **uplo** = **Nag_Lower**, a similar statement holds for the computed factors L and D .

8 Further Comments

The elements of D overwrite the corresponding elements of A ; if D has 2 by 2 blocks, only the upper or lower triangle is stored, as specified by **uplo**.

The unit diagonal elements of U or L and the 2 by 2 unit diagonal blocks are not stored. The remaining elements of U or L are stored in the corresponding columns of the array **a**, but additional row interchanges must be applied to recover U or L explicitly (this is seldom necessary). If **ipiv**[$i - 1$] = i , for $i = 1, 2, \dots, n$ (as is the case when A is positive-definite), then U or L is stored explicitly (except for its unit diagonal elements which are equal to 1).

The total number of real floating-point operations is approximately $\frac{4}{3}n^3$.

A call to this function may be followed by calls to the functions:

nag_zhetrs (f07msc) to solve $AX = B$;

nag_zhecon (f07muc) to estimate the condition number of A ;

nag_zhetri (f07mwc) to compute the inverse of A .

The real analogue of this function is nag_dsytrf (f07mdc).

9 Example

To compute the Bunch–Kaufman factorization of the matrix A , where

$$A = \begin{pmatrix} -1.36 + 0.00i & 1.58 + 0.90i & 2.21 - 0.21i & 3.91 + 1.50i \\ 1.58 - 0.90i & -8.87 + 0.00i & -1.84 - 0.03i & -1.78 + 1.18i \\ 2.21 + 0.21i & -1.84 + 0.03i & -4.63 + 0.00i & 0.11 + 0.11i \\ 3.91 - 1.50i & -1.78 - 1.18i & 0.11 - 0.11i & -1.84 + 0.00i \end{pmatrix}.$$

9.1 Program Text

```
/* nag_zhetrf (f07mrc) Example Program.
 *
 * Copyright 2001 Numerical Algorithms Group.
 *
 * Mark 7, 2001.
 */

#include <stdio.h>
#include <nag.h>
#include <nag_stdlib.h>
#include <nagf07.h>
#include <nagx04.h>
```

```

int main(void)
{
    /* Scalars */
    Integer i, j, n, pda;
    Integer exit_status=0;
    Nag_UploType uplo_enum;
    Nag_MatrixType matrix;

    NagError fail;
    Nag_OrderType order;
    /* Arrays */
    Integer *ipiv=0;
    char    uplo[2];
    Complex *a=0;

#ifdef NAG_COLUMN_MAJOR
#define A(I,J) a[(J-1)*pda + I - 1]
    order = Nag_ColMajor;
#else
#define A(I,J) a[(I-1)*pda + J - 1]
    order = Nag_RowMajor;
#endif

    INIT_FAIL(fail);
    Vprintf("f07mrc Example Program Results\n\n");

    /* Skip heading in data file */
    Vscanf("%*[\n] ");
    Vscanf("%ld%*[\n] ", &n);
#ifdef NAG_COLUMN_MAJOR
    pda = n;
#else
    pda = n;
#endif

    /* Allocate memory */
    if ( !(ipiv = NAG_ALLOC(n, Integer)) ||
        !(a = NAG_ALLOC(n* n, Complex)) )
    {
        Vprintf("Allocation failure\n");
        exit_status = -1;
        goto END;
    }
    /* Read A from data file */
    Vscanf(" ' %ls '%*[\n] ", uplo);
    if (*(unsigned char *)uplo == 'L')
    {
        uplo_enum = Nag_Lower;
        matrix = Nag_LowerMatrix;
    }
    else if (*(unsigned char *)uplo == 'U')
    {
        uplo_enum = Nag_Upper;
        matrix = Nag_UpperMatrix;
    }
    else
    {
        Vprintf("Unrecognised character for Nag_UploType type\n");
        exit_status = -1;
        goto END;
    }

    if (uplo_enum == Nag_Upper)
    {
        for (i = 1; i <= n; ++i)
        {
            for (j = i; j <= n; ++j)
                Vscanf(" ( %lf , %lf )", &A(i,j).re, &A(i,j).im);
        }
        Vscanf("%*[\n] ");
    }
}

```

```

    }
else
{
    for (i = 1; i <= n; ++i)
    {
        for (j = 1; j <= i; ++j)
            Vscanf(" ( %lf , %lf )", &A(i,j).re, &A(i,j).im);
    }
    Vscanf("%*[\n] ");
}

/* Factorize A */
f07mrc(order, uplo_enum, n, a, pda, ipiv, &fail);
if (fail.code != NE_NOERROR)
{
    Vprintf("Error from f07mrc.\n%s\n", fail.message);
    exit_status = 1;
    goto END;
}

/* Print factor */
x04dbc(order, matrix, Nag_NonUnitDiag, n, n, a, pda, Nag_BracketForm,
        "%7.4f", "Details of Factorisation", Nag_IntegerLabels, 0,
        Nag_IntegerLabels, 0, 80, 0, 0, &fail);
if (fail.code != NE_NOERROR)
{
    Vprintf("Error from x04dbc.\n%s\n", fail.message);
    exit_status = 1;
    goto END;
}

/* Print pivot indices */
Vprintf("\nIPIV\n");
for (i = 1; i <= n; ++i)
    Vprintf("%3ld%s", ipiv[i-1], i%7==0 ? "\n": " ");
Vprintf("\n");
END:
if (ipiv) NAG_FREE(ipiv);
if (a) NAG_FREE(a);
return exit_status;
}

```

9.2 Program Data

f07mrc Example Program Data

4	:Value of N
'U'	:Value of UPLO
(-1.36, 0.00) (1.58, 0.90) (2.21,-0.21) (3.91, 1.50)	
(-8.87, 0.00) (-1.84,-0.03) (-1.78, 1.18)	
(-4.63, 0.00) (0.11, 0.11)	
(-1.84, 0.00)	:End of matrix A

9.3 Program Results

f07mrc Example Program Results

Details of Factorisation				
	1	2	3	4
1	(-1.3600, 0.0000)	(3.9100, 1.5000)	(0.3100,-0.0433)	(-0.1518,-0.3743)
2		(-1.8400, 0.0000)	(0.5637,-0.2850)	(0.3397,-0.0303)
3			(-5.4176, 0.0000)	(0.2997,-0.1578)
4				(-7.1028, 0.0000)

IPIV			
-4	-4	3	4
